



SECTION 2. FORMS PTO/SB/08A and 08B (formerly Form PTO-1449)**IN THE UNITED STATES PATENT AND TRADEMARK OFFICE**

Applicants: Kamen et al. Attorney Docket: 1062/D28
Serial No: 10/618,082 Art Group Unit: Not yet assigned
Date Filed: July 11, 2003 Examiner Name: Not yet assigned
Invention: Motion Control of a Transporter

**LIST OF PATENTS AND PUBLICATIONS FOR
APPLICANT'S INFORMATION DISCLOSURE STATEMENT**

Ref. No.	U.S. Patent No.	Inventor	Issue Date	See Sec. 1	Exam. Init.
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AB	849,270	Schafer et al.	Apr. 2, 1907		
AC	1,739,716	Fisher	Dec. 17, 1929		
AD	2,742,973	Johannesen, H.	Apr. 24, 1956		
AE	3,145,797	Taylor	Aug. 25, 1964		
AF	3,260,324	Suarez	July 12, 1966		
AG	3,283,398	Andren	Nov. 8, 1966		
AH	3,374,845	Selwyn, D.	Mar. 26, 1968		
AI	3,399,742	Malick	Sept. 3, 1968	*	
AJ	3,446,304	Alimanestiano	May 1969		
AK	3,450,219	Fleming, J.	June 17, 1969		
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AR	3,952,822	Udden et al.	Apr. 27, 1976		
AS	3,967,862	Hunter et al.	July 1976		
AT	4,018,440	Deutsch	Apr. 19, 1977		
AU	4,062,558	Wasserman	Dec. 13, 1977		
AV	4,076,270	Winchell	Feb. 28, 1978		
AW	4,088,199	Trautwein	May 9, 1978		
AX	4,094,372	Notter	June 13, 1978		
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AZ	4,111,445	Haibeck	Sept. 5, 1978		
BA	4,151,892	Francken	May 1, 1979	*	
BB	4,222,449	Feliz	Sept. 16, 1980		
BC	4,264,082	Fouchey, Jr.	Apr. 28, 1981		
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BJ	4,375,840	Campbell	Mar. 8, 1983		
BK	4,510,956	King	Apr. 16, 1985		
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BM	4,566,707	Nitzberg	Jan. 28, 1986		
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BS	4,685,693	Vadjunec	Aug. 11, 1987		
BT	4,709,772	Brunet	Dec. 1, 1987		
BU	4,716,980	Butler	Jan. 5, 1988		
BV	4,740,001	Torleumke	Apr. 26, 1988		
BW	4,746,132	Eagan	May 24, 1988		
BX	4,770,410	Brown	Sept. 13, 1988		
BY	4,786,069	Tang	Nov. 22, 1988		
BZ	4,790,400	Sheeter	Dec. 13, 1988		
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CB	4,794,999	Hester	Jan. 3, 1989		
CC	4,798,255	Wu	Jan. 17, 1989		
CD	4,802,542	Houston et al.	Feb. 7, 1989		
CE	4,809,804	Houston et al.	Mar. 7, 1989		
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CJ	4,874,055	Beer	Oct. 17, 1989		
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CS	5,011,171	Cook	Apr. 30, 1991		
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DL	5,655,615	Mick	Aug. 1997		
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DN	5,701,968	Wright-Ott et al.	Dec. 1997		
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EM	DE 298 08 091 U1	Brecht	Oct. 10, 1998		
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ER	DE 44 04 594 A 1	Wittelsberger (and translation)	Aug. 17, 1995		
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EV	EP 0 109 927	von Rohr	July 4, 1984		
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FG	JP 0255580	Takahashi (with abstract)	Dec. 17, 1985		<i>sf</i>
FH	JP 7255780		Mar. 1995		
FI	JP 57-87766	Iguchi (with abstract)	June 1982		<i>sf</i>
FJ	JP 52-44933	Shimizu (with abstract)	Oct. 1975		<i>sf</i>
FK	JP 63-305082	Santo (with abstract and translation)	Dec. 1988		<i>sf</i>
FL	JP 62-12810	Hitachi	July 10, 1985		
FM	JP 57-110569		7 Sep. 1982		
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FU	WO 98/46474	Staelin et al.	Oct. 22, 1998		<i>sf</i>
FV	WO 00/73101	Deka Products LP	7 Dec. 2000	*	<i>sf</i>
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FZ	Schoonwinkel, A., <i>Design and Test of a Computer-Stabilized Unicycle</i>, Stanford University (1988), UMI Dissertation Services		_____
GA	Vos, D., <i>Dynamics and Nonlinear Adaptive Control of an Autonomous Unicycle</i>, Massachusetts Institute of Technology, 1989		_____
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GF	Watson Industries, Inc., <i>Vertical Reference Manual</i>, ADS-C132-1A, 1992, pp. 3-4		_____
GG	News article <i>Amazing Wheelchair Goes Up and Down Stairs</i>		_____
GH	Osaka et al., <i>Stabilization of unicycle, Systems and Control</i>, Vol. 25, No. 3, Japan 1981, pp. 159-166 (Abstract Only)		_____
GI	Roy et al., <i>Five Wheel Unicycle System</i>, <i>Medical & Biological Engineering & Computing</i>, Vol. 23, No. 6, United Kingdom 1985, pp. 593-596		_____

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GJ	Kawaji, S., <i>Stabilization of Unicycle Using Spinning Motion</i>, <u>Denki Gakkai Ronbushi, D</u>, Vol. 107, Issue 1, Japan 1987, pp. 21-28 (Abstract Only)		
GK	Schoonwinkel, A., <i>Design and Test of a Computer-Stabilized Unicycle</i>, <u>Dissertation Abstracts International</u>, Vol. 49/03-B, Stanford University 1988, pp. 890-1294 (Abstract only)		
GL	Vos et al., <i>Dynamics and Nonlinear Adaptive Control of an Autonomous Unicycle - Theory and Experiment</i>, <u>American Institute of Aeronautics and Astronautics</u>, A90-26772-10-39, Washington, D.C. 1990, pp. 487-494 (Abstract only)		
GM	TECKNICO'S Home Page, <i>Those Amazing Flying Machines</i> , http://www.swiftsite.com/teehnieo		
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GQ	Yamafuji & Kawamura, <i>Study of Postural and Driving Control of Coaxial Bicycle</i> , <u>Paper Read at Meeting of Japan Society of Mechanical Engineering (Series C)</u> , vol. 54, no. 501, (May, 1988), pp. 1114-21		af
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GS	Momoi & Yamafuji, <i>Motion Control of the Parallel Bicycle-Type Mobile Robot Composed of a Triple Inverted Pendulum</i> , <u>Paper Read at Meeting of Japan Society of Mechanical Engineering (Series C)</u> , vol. 57, no. 541, (Sep., 1991), pp. 154-159		af

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GU	Ulmea Institute of Design Degree Show 2002, Car Design News, http://www.cardecugbbows.ein/features/2002/020804ulmea-show/	*	—
GV	International Search Report of November 7, 2003	*	—

Examiner Signature: *A. J. J. J.*

Date Considered: 11/26/04

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw line through citation *if not* in conformance and not considered. Include copy of this form with next communication to applicant.

SECTION 2. FORMS PTO/SB/08A and 08B (formerly Form PTO-1449)

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicants: Kamen et al. Attorney Docket: 1062/D28
Serial No: 10/618,082 Art Group Unit: 3611
Date Filed: July 11, 2003 Examiner Name: Avraham, A.
Invention: Motion control of a Transporter

**LIST OF PATENTS AND PUBLICATIONS FOR
APPLICANT'S INFORMATION DISCLOSURE STATEMENT**

U.S. PATENT DOCUMENTS					
Examiner Initials	Reference Number	Document Number	Issue Date Pub. No.	Inventor	Class/Subclass
<i>AF</i>	GW	US 20040069543 A1	Apr. 15, 2004	Kamen et al.	180/7.1

Examiner Signature: _____

Date Considered: _____

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw line through citation *if not* in conformance and not considered. Include copy of this form with next communication to applicant.